```
camera _open();
//Opens the connection to the camera

camera_close();
//Closes the connection to the camera

camera_update();
//Gets a new image from the camera and performs color tracking

get_object_count (channel #);
//The number of objects being tracked on the specified color channel

get_object_center_x(channel #, object #)
// The center column (x) coordinate value of the object # on the color channel

get _object_center_y(channel #, object #)
// The center row (y) coordinate value of the object # on the color channel
```